

Topological Complexity and Motion Planning in Certain Real Grassmannians

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INTRODUCTION: Topological Complexity of a space

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An instrument to measure this discontinuity is the topological complexity of the space X .

A main reason of interest in this quantity is that it is a homotopy invariant of the configuration space.

INTRODUCTION: Topological Complexity of a space

Definition

The topological complexity of the space X , $TC(X)$, is the minimal number k such that there exists an open cover $X \times X = U_1 \cup \dots \cup U_k$ with the property that each U_i admits a continuous motion planner $s_i: U_i \rightarrow PX$.

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Proposition 1 For a path-connected topological space X it holds

$$cat(X) \leq TC(X) \leq cat(X \times X) \leq 2cat(X) - 1.$$

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Proposition 2 Given two polyhedra X and Y one has

$$TC(X \times Y) \leq TC(X) + TC(Y) - 1.$$

TC of Spaces with Small Fundamental Group

Theorem (1)

If X is an r -connected simplicial polyhedron with covering dimension $\dim X$, then

$$TC(X) < \frac{2 \dim X + 1}{r + 1} + 1.$$

In particular we have the general bound

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Theorem (2)

Let X be a cell complex with $\pi_1(X) = \mathbb{Z}_2$. Then

$$TC(X) \leq 2 \dim(X).$$

Furthermore, for a closed manifold X with $\pi_1(X) = \mathbb{Z}_2$ it holds that

$$TC(X) \leq 2 \dim(X) - 1$$

TC of Spaces with Small Fundamental Group

Theorem (3)

For a closed connected n -dimensional manifold X with $\pi_1(X) = \mathbb{Z}_2$ one has $\text{cat}(X) = \dim(X) + 1$ if and only if $\omega^n = 0 \in H^n(X; \mathbb{Z}_2)$ where $\omega \in H^1(X; \mathbb{Z}_2)$ is the generator.

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Theorem (4)

Let X be a finite cell complex such that $\pi_1(X) = \mathbb{Z}_3$.

- 1 Assume that either $\dim X$ is odd or $\dim X = 2n$ is even and the 3-adic expansion of n contains at least one digit 2. Then, $\text{TC}(X) \leq 2 \dim(X)$.
- 2 For any integer $n \geq 1$ having only the digits 0 and 1 in its 3-adic expansion there exists a finite polyhedron X of dimension $2n$ with $\pi_1(X) = \mathbb{Z}_3$ and $\text{TC}(X) = 2 \dim(X) + 1$.

Definition

Let V be a finite-dimensional vector space over a field \mathbb{k} . The Grassmannian $\text{Gr}(k, V)$ is the set of all k -dimensional linear subspaces of V . If V has dimension n , then the Grassmannian is also denoted $\text{Gr}(k, n)$, and if the underlying field is \mathbb{R} this Grassmannian is also denoted $G_k(\mathbb{R}^n)$ we can write, by identification, $G_k(\mathbb{R}^n) = O(n)/(O(k) \times O(n-k))$ where $O(n)$ is the orthogonal group.

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Let $G_k(\mathbb{R}^{n+k})$ be the set of all real k -dimensional subspaces of \mathbb{R}^{n+k} . $G_k(\mathbb{R}^{n+k})$ is a compact connected differentiable manifold of real dimension nk with $\pi_1(G_k(\mathbb{R}^{n+k})) = \mathbb{Z}_2$. In particular, $G_1(\mathbb{R}^{n+1}) = \mathbb{R}P^n$.

Topological Complexity of Grassmannians

From **theorem (2)** we have the upper bound $TC(G_k(\mathbb{R}^{n+k})) \leq 2kn$.
Moreover, it follows from **theorem (2)** and **theorem (3)** that $TC(G_k(\mathbb{R}^{n+k})) \leq 2kn-1$.

In [I. Berstein, **On the Lusternik-Schnirelmann category of Grassmannians**], the author shows that in some cases

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Notice that by applying the upper bound given by **Proposition 1** only allows to establish the general dimensional upper bound $TC(G_k(\mathbb{R}^n)) \leq 2kn+1$.

Definition

We define $\text{ht}(\omega_1)$, the height of ω_1 , to be $\text{ht}(\omega_1) := \sup\{m; \omega_1^m \neq 0 \in H^*(G_k(\mathbb{R}^{n+k}); \mathbb{Z}_2)\}$.

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Proposition 3 (R. Stong, **Cup products in Grassmannians**, Topology Appl. 13, 103-113, (1982))

In $G_k(\mathbb{R}^{n+k})$, for $2 \leq k \leq n$ with $2^s < n + k \leq 2^{s+1}$, we have

$$\text{ht}(\omega_1) = \begin{cases} 2^{s+1} - 2, & \text{if } k = 2 \text{ or if } k = 3 \text{ and } n + k = 2^s + 1, \\ 2^{s+1} - 1, & \text{otherwise.} \end{cases}$$

Theorem (5)

For $2 \leq k \leq n$ with $2^s < n + k \leq 2^{s+1}$, we have the following .

- 1 If $k=2$, then $TC(G_2(\mathbb{R}^{n+2})) \geq n$.
- 2 If $k=3$ and if $n + 3 = 2^s + 1$, then $TC(G_3(\mathbb{R}^{n+3})) \geq 2n + 2$.
If $k = 3$ and if $n + 3 \neq 2^s + 1$, then $TC(G_3(\mathbb{R}^{n+3})) \geq n + 2$.
- 3 If $4 \leq k \leq n$, then $TC(G_k(\mathbb{R}^{n+k})) \geq n + k - 1$.

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Proof.

We apply **Proposition 1** to see that $TC(G_k(\mathbb{R}^{n+k})) \geq \text{cat}(G_k(\mathbb{R}^{n+k})) \geq \text{ht}(\omega_1)$ and the assertions follow from **Proposition 3**. \square

EXAMPLE

$\text{TC}(\mathbf{G}_2(\mathbb{R}^4))$

It is a quick observation from **Proposition 1** and **Theorem (5)** that

$$2 \leq \text{TC}(\mathbf{G}_2(\mathbb{R}^4)) \leq 9.$$

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In [H. Hiller, **On the cohomology of real Grassmannians**, p. 529], it is shown that $\text{cat}(\mathbf{G}_2(\mathbb{R}^{2^s+2})) = 2^{s+1} - 1$. Thus, $\text{cat}(\mathbf{G}_2(\mathbb{R}^4)) = 3$. By **Theorem (5)**, we see that $3 \leq \text{TC}(\mathbf{G}_2(\mathbb{R}^4)) \leq 5$. □

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In [K.J.PEARSON AND TAN ZHANG, **Topological Complexity and Motion Planning in Certain Real Grassmannians**] there it was wrongly assumed that $\text{TC}(X) = \text{cat}(X \times X)$ (Theorem 1.8). This compromises the result " $\text{TC}(G_2(\mathbb{R}^4)) = 5$ "

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